

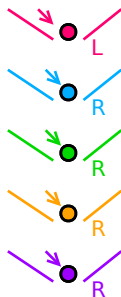
# Characteristic Cascades

Rasmus K. Rendsvig  
Roskilde

Vincent F. Hendricks  
Copenhagen / Columbia

Commemorative Colloquium for Horacio Arlo-Costa  
CFE Carnegie Mellon University  
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# Introduction



## Informational Cascade

- Each agent acts in turn, based on a *private* and a *public signal*.
- There is a *tipping point* after which previous agents' choices dominate, and a *cascade* is started.

# Basic Idea

We have a set of agents  $I = \{1, 2, \dots, n\}$ , which act in turn. Each turn goes:

1. Agent  $i$  has some beliefs based on a *private signal* (prior beliefs, issued ticket,...).
2. The agent receives a *public signal* by the actions of agents  $1, \dots, i - 1$ .  
This produces first model for agent  $i$ ,  $M_i$ .
3. The agent *deliberates* by considering presented information.  
This produces second model for agent  $i$ ,  $M'_i$ .
4. Based on  $M'_i$ , the agent applies a *decision rule* and acts.

The outcome depends on the *interpretation rule* used in step 2, the *merge rule* in step 3 and the *decision rule* in step 4

# Background: Plausibility Models

## Models:

$$M = (S, \sim_i, \leq_i, \|\cdot\|)_{i \in I}$$

- ❶  $S$  is a finite set of *states*.
- ❷  $\sim_i$  is an equivalence relation on  $S$ , for each  $i \in I$ . Let  $i(s) = \{t : s \sim_i t\}$ .
- ❸  $\leq_i$  is a preorder locally connected in  $i(s)$ , for all  $s \in S$ .
- ❹  $\|\cdot\|$  is a valuation map,  $\|\cdot\| : \Phi \longrightarrow \mathcal{P}(S)$ .

## Language:

$\Phi = \{p\}$  and set  $L := p$ ,  $R := \neg p$ . For  $i \in I$ , wff are:

$$p \mid \neg\varphi \mid \varphi \wedge \psi \mid B_i\varphi \mid K_i\varphi$$

## Semantics:

$M, s \models p$  iff  $s \in \|p\|$

$M, s \models B_i\varphi$  iff  $\forall t \in \text{Min}_{\leq_i}(i(s)) : M, t \models \varphi$  wh.

$\text{Min}_{\leq_i} = \{t \in i(s) : t \leq_i s', \text{ for all } s' \in i(s)\}$

$M, s \models K_i\varphi$  iff  $\forall t \in i(s) : M, t \models \varphi$

## Interpretation:

Minimal means Most Plausible (“*less means more*”):  $s <_i t$  “=”  $s \longleftarrow_i t$ .

# Signals and Actions

## Actions:

$$\alpha = \{L, R\}, \alpha_i \in \alpha.$$

Denote by  $\sigma$  the full string of chosen actions:  $\sigma = \alpha_1, \alpha_2, \dots, \alpha_n$

## Private Signal:

$$\sigma_i \in \alpha \cup \{\lambda\}$$

$\sigma_i$  forms the agent's initial, "private" beliefs about  $L/R$ :

If  $\sigma_i = L/R$ , then  $M_{i,s_0} \models B_i(L/R)$

## Public signal:

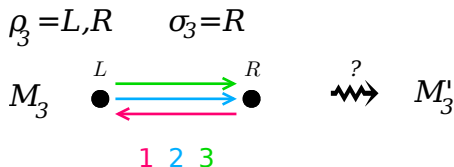
Initial segment of  $\sigma$  of length  $i - 1$ :

$$\rho_i = \alpha_1, \dots, \alpha_{i-1}.$$

$\rho_1 = \lambda$ , the empty string.

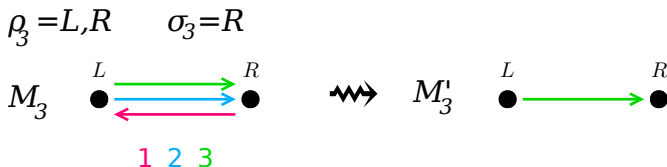
$\rho_i$  forms the agent's higher order beliefs depending on interpretation of actions.

# Deliberation?



- We just want the agents to count heads
  - ▶ Order of previous agents does not matter
  - ▶ This means conservative ( $\uparrow_i L, \uparrow_i R$ ) / radical upgrade ( $\uparrow_i L, \uparrow_i R$ ) does not work ( $i$ 's beliefs will just oscillate)
- No Priority
  - ▶ So Priority Merge ( $R_{j \otimes i}$ ) and Lexicographic Merge ( $R_{j/i}$ ) is out:  $i$  will just believe  $j$ .
- Has this been treated in the literature? Can we use things from judgment aggregation?
- Here, we construct a merge procedure: *Majority Merge*

# Majority Merge



**Majority merge** is a belief upgrade method by which a single agent can change his beliefs regarding  $p$  based on the perceived beliefs of a group of other agents.

The idea behind the merge is 'head counting': agent  $i$  compares how many agents  $j$  in group  $G$  hold that  $s <_j t$  for some two states  $s$  and  $t$ , and **adopts the opinion of the majority**.

# Majority Merge

For agent  $a$  and group  $G$  and  $L/R$ :

- 1 For each  $i$ , find  $\prec_i = \prec_i \cap \bigcap_{i \in G} \sim_i$ .
- 2 Find  $\prec = \biguplus_{i \in G} \prec_i$ , the multiset sum of  $\prec_i, i \in I$ .
- 3 Remove symmetries: if there are pairs  $(s, t)$  and  $(t, s)$  in  $\biguplus_{i \in G} \prec_i$  then remove one of each until only one direction remains. Denote the resulting set  $\vec{\prec}$ .
- 4 Set  $\leq'_a := \vec{\prec} \cup (\sim_a \cap \|L\| \times \|L\|) \cup (\sim_a \cap \|R\| \times \|R\|)$ , closed under transitivity.

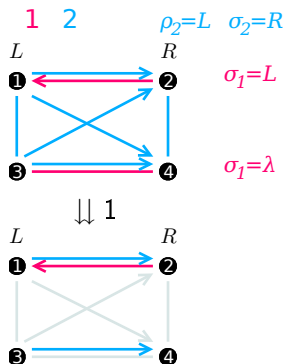
If the states are arranged properly this amounts to **counting horizontal arrows** (1-3) and **restoring the information cell** (4)

# Majority Merge: Example 1

Step 1. For each  $i$ , find  $\prec_i = \prec_i \cap \bigcap_{i \in G} \sim_i$ .

$$\prec_1 = \{(1, 2)\}$$

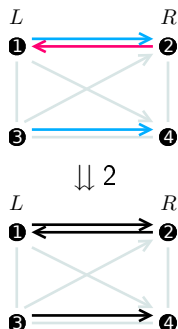
$$\prec_2 = \{(2, 1), (4, 3)\}$$



# Majority Merge: Example 1

Step 2. Find  $\prec = \biguplus_{i \in G} \prec_i$ , the multiset sum of  $\prec_i, i \in I$ .

$$\prec = \biguplus_{i \in G} \prec_i = \prec_1 \biguplus \prec_2 = \{(1,2), (2,1), (4,3)\}$$

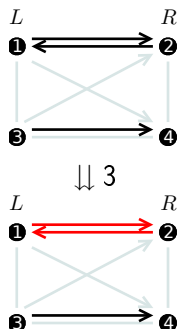


# Majority Merge: Example 1

Step 3. Remove symmetries: if there are pairs  $(s, t)$  and  $(t, s)$  in  $\biguplus_{i \in G} \prec_i$  then remove one of each until only one direction remains. Denote the resulting set  $\bar{\prec}$ .

$$\prec_1 \biguplus \prec_2 = \{(1, 2), (2, 1), (4, 3)\}$$

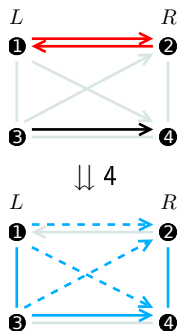
$$\bar{\prec} = \{(4, 3)\}$$



# Majority Merge: Example 1

Step 4. Set  $\leq'_a := \bar{\sim} \cup (\sim_a \cap \|L\| \times \|L\|) \cup (\sim_a \cap \|R\| \times \|R\|)$ , closed under transitivity.

$$\begin{aligned} \leq'_a &= \{(4, 2)\} \\ &\cup \{(1, 1), (1, 3), (3, 1), (3, 3)\} \\ &\cup \{(2, 2), (2, 4), (4, 2), (4, 4)\} \\ &\cup \{(2, 1), (2, 3), (4, 1)\} \end{aligned}$$



So, being given  $\rho_2 = L$  and  $\sigma_2 = R$ , after deliberation  $M'_2, 1 \models B_2 R$

# Majority Merge: Example 2

Step 1. Take the horizontal arrows

Step 2. Ignore their colors (mash them together)

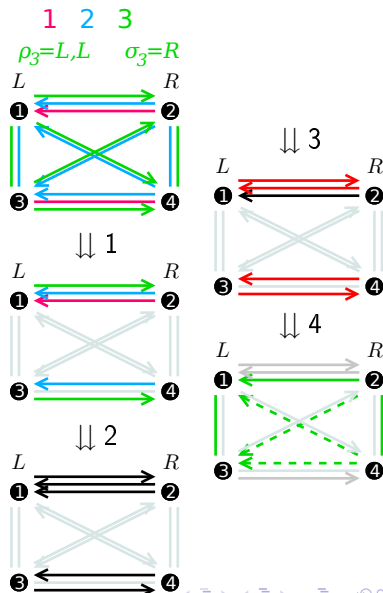
Step 3. Remove conflicting pairs

Step 4. Restore information cell and establish preorder

Being given  $\rho_3 = L, L$  and  $\sigma_3 = R$ , after deliberation  $M'_3, 1 \models B_3 L$

3 changes his mind after deliberation!

Based on  $M'_3$ , 3 chooses his action based on a *decision rule*.



# Decision Rules

## If decided:

If the agent thinks he should go  $\varphi$ , he goes  $\varphi$ :

$$\text{If } M'_i, 1 \models B_i \varphi \text{ then } \alpha_i = \varphi$$

## What if he is indifferent?

If  $M'_i, 1 \models \neg B_i L \wedge \neg B_i R$  then  $\alpha_i = \text{default}$

*default* rules:

- $\alpha_i = \sigma_i$  (used here for naïve agents)
- Randomize over  $\{L, R\}$  (used here for open-minded agents)
- $\alpha_i = \alpha_{i-1}$
- Play mixed strategy with probabilities given by  $\alpha_1, \dots, \alpha_{i-1}$
- ...

# Tipping Point

**Tipping Point:** Define action  $\alpha_i$  to be a *tipping point* in the (partial) string

$$\sigma_{<i+1} = \alpha_1 \dots \alpha_{i-1} \alpha_i$$

if, and only if, for all possible *consistent* strings

$$\sigma_{i>} = \alpha_{i+1} \dots \alpha_n$$

extending  $\sigma_{<i+1}$ , it holds that for all

$$\alpha_j \in \sigma_{i>}, \alpha_j = \alpha_i$$

**Consistent string:** (loosely) a string is consistent if, given each agent's interpretation of their public signals, they acted in accordance with the decision rules.

In Example 2, the string  $L, L, R$  is *not* consistent.

If agent 3 had interpreted  $p_3 = L, L$  differently so he was indifferent between  $L$  and  $R$  after deliberation and then randomized, then it would be.

## Case 1: Naïve Agents

### Interpretation Rule:

Where  $j < i$  and  $\varphi = \{L, R\}$

$$\text{if } \alpha_j = \varphi \text{ then } M_i, 1 \models B_i B_j \varphi$$

### Default rule:

$$\text{if } M'_i, 1 \models \neg B_i L \wedge \neg B_i R \text{ then } \alpha_i := \sigma_i$$

### Private signals:

$$\sigma_1 = L$$

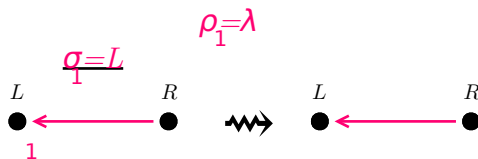
$$\sigma_2 = R$$

$$\sigma_3 = R$$

$$\sigma_4 = R$$

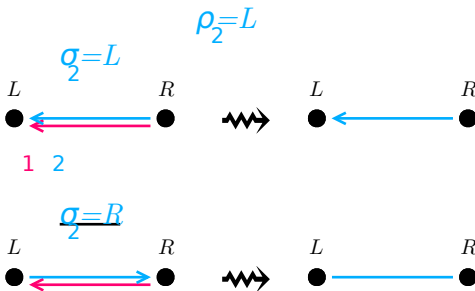
$$\sigma_5 = !$$

# Case 1, Agent 1



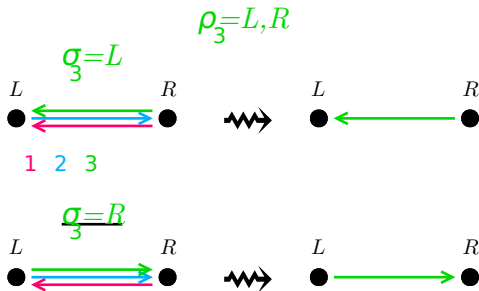
$M'_1, 1 \models B_1 L$  so  $\alpha_1 = L$

## Case 1, Agent 2



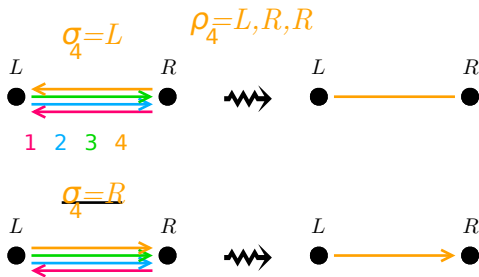
$M'_2, 1 \models \neg B_2 L \wedge \neg B_2 R$  so  $\alpha_2 = \text{default} = \sigma_2 = R$

# Case 1, Agent 3



$M'_3, 1 \models B_3 R$  so  $\alpha_3 = R$

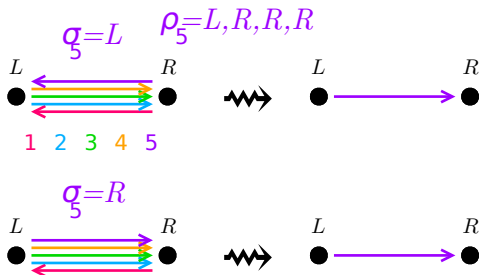
## Case 1, Agent 4



If  $\sigma_4 = L$ , then  $M'_4, 1 \models \neg B_4 L \wedge \neg B_4 R$  so  $\alpha_4 = \text{default} = \sigma_4 = L$   
 $\Rightarrow$  Back to agent 2 situation of indifference.

If  $\sigma_4 = R$ , then  $M'_4, 1 \models B_4 R$  so  $\alpha_4 = R$ .

## Case 1, Agent 5



No matter which signal 5 gets,  $M'_5, 1 \models B_5 R$  so  $\alpha_5 = R$   
 And so on for  $i > 5$ .

**So  $\alpha_4 = R$  was tipping point!**

## Conclusion, case 1

- There was a tipping point, being the action of agent 4: if  $\alpha_4 = R$ , then all subsequent agents would go right.
- General: if there are ***two more*** agents choosing one action than there are agents choosing the other action, a cascade will commence.
- This is caused by, amongst others, equal weights of the arrows and the naïve interpretation rule.

## Case 2: Open-minded agents

### Interpretation Rule:

Consider all possibilities consistent with private signal  $\sigma_j \in \{L, \lambda, R\}$  for  $j < i$ , and the default rule.

( $\lambda$ : Open-minded agents consider it possible that the agents before did not have an initial preference wrt.  $L$  and  $R$ )

### Default Rule:

if  $M'_i, 1 \models \neg B_i L \wedge \neg B_i R$  then randomize over  $\{L, R\}$

### Private signals:

$$\sigma_1 = L$$

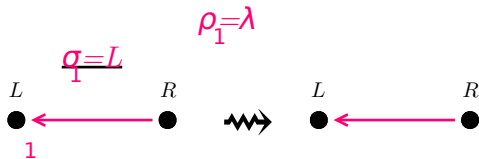
$$\sigma_2 = R$$

$$\sigma_3 = R$$

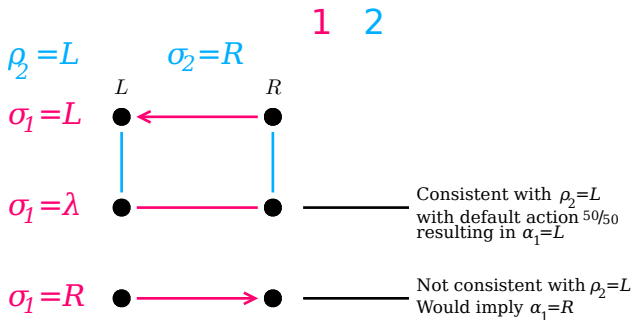
$$\sigma_4 = R$$

$$\sigma_5 = !$$

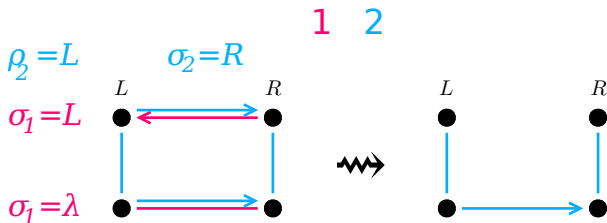
## Case 2, Agent 1



## Case 2 – what does 2 consider?



Case 2, Agent 2,  $M_2 \rightsquigarrow M'_2$


$$M'_{2,1} \models B_2 R, \text{ so } \alpha_2 = R$$

## Case 2: Agents 3, 4 and 5

**Agent 3:** 3 knows that  $\sigma_2 = R$ .

Otherwise,  $\alpha_2 \neq R$  as 2 would be convinced by agent 1's action.

After deliberation, 3 believes  $R$ , so  $\alpha_3 = R$ .

**Agent 4:** 4 knows that  $\sigma_3 \neq L$ , but maybe  $\sigma_3 = R$  or  $\sigma_3 = \lambda$ .

$\sigma_3 = L$  is inconsistent with  $\rho_4 = L, R, R$

$\sigma_3 = R$  is consistent with  $\rho_4 = L, R, R$

$\sigma_3 = \lambda$  is consistent with  $\rho_4 = L, R, R$

3 was indifferent, randomized and played  $R$ .

After deliberation, 4 believes  $R$ , so  $\alpha_4 = R$ .

## Case 2: Agents 3, 4 and 5

**Agent 5:** 5 cannot rule out anything!

$\sigma_4 = L$  is consistent with  $\rho_5 = L, R, R, R$ : 4 was indifferent, randomized and played  $R$

$\sigma_4 = R$  is consistent with  $\rho_5 = L, R, R, R$

$\sigma_4 = \lambda$  is consistent with  $\rho_5 = L, R, R, R$ : 4 was convinced by 2 and 3.

After deliberation: if  $\sigma_5 = R$ , then  $B_5 R$ . If  $\sigma_5 = L$ , then indifferent so  $\alpha_5 = \text{default}$ .

**Agent 6:** Cannot rule out anything, etc. and so on for  $j > 6$ .

**Upshot:** An agent that receives private signal  $L$  will divert to *default*, and hence possibly play  $L$ .

Therefore *there will always be a possible consistent string where for*  
 $j > i, \alpha_j \neq \alpha_i$

Hence, there can be no tipping point.

# Conclusions

- Naïve agents will cause a cascade if *two more* choose one action over the other.
- Open-Minded agents will *never* cause a cascade.
  - ▶ Open-minded agents will not fall in the lemming trap: they will consider it possible that previous agents acted on a weak basis, and will therefore be indifferent after deliberation.
- **Overall:** considering higher-order information has an effect: considering more possibilities eliminates cascade.

## Further perspectives

- 1st vs. 3rd person: all this is from the modelers point of view. What happens if we limit visibility so agents only perceive the last say 3 agents?
- How will knowledge or belief about interpretation and decision rules affect things?
- Other “lemming effect” scenarios:
  - ▶ Going to the party: two unknowing agents leading a flock astray.
  - ▶ Causing Jaywalkers: knowing agent leading unknowing agents across red light (and into traffic!)
  - ▶ ...